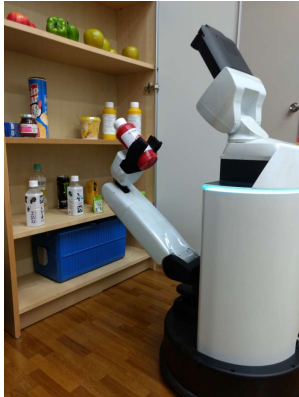
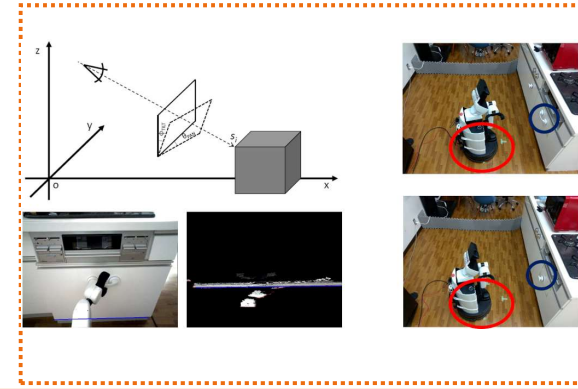


eR@sers (Japan)



Development point

We use a multimodal system for active robot-object interaction using laser-based SLAM, RGBD images, and contact sensors.



Introduction of your team

Team eR@sers (erasers) mainly focuses on the adaptability to the environmental changes, and on the integration between the sensory-motor data and symbolic representation, utilizing only the neuro-dynamical model, where almost all training data comes from physical environments and the system testing is performed and evaluated in the real scenarios.

Role	Name	Affiliation/Title	Specialty, Field of study
Team Leader	Luis Contreras	Tamagawa Univ. / Postdoc	Computer Science
	Yoshiaki Mizuchi	Tamagawa Univ. / Asst. prof.	Computer Science
	Arata Sakamaki	Tamagawa Univ. / Master student	Computer Science
	Hibiki Kawakami	Tamagawa Univ. / Undergrad. student	Computer Science
	Masaki Fujita	Tamagawa Univ. / Undergrad. student	Computer Science
	Ryohei Kobayashi	Tamagawa Univ. / Undergrad. student	Computer Science
	Reiji Nakano	Tamagawa Univ. / Undergrad. student	Computer Science
	Ryuji Iino	Tamagawa Univ. / Undergrad. student	Computer Science
	Kensuke Suzuki	Tamagawa Univ. / Undergrad. student	Liberal Arts
	Leo Miura	Tamagawa Univ. / Undergrad. student	Computer Science



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HP etc. <https://trcp.gitlab.io/erasers/>