

# EPANer (France)



## Development point

We endow the robot the amazing ability to perceive dynamic and static objects in our daily life, manipulate them and move around us, smartly.



EPANer Robotics Team

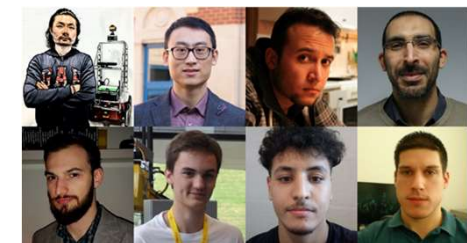
**Faster**  
**Higher**  
**Stronger**  
**Together**  
**EPANer**

## Introduction of your team

【Inspiration, motivation to form a team】 Our team was established in early 2018 with the valuable support of Toyota and WRS, aiming to participate in various robotic challenges.

【Future outlook】 Our objective is to promote robotic technologies to enhance the quality of life and well-being.

Role	Name	Affiliation/Title	Specialty, Field of study
Team leader	Zhi Yan	UTBM, CIAD Lab, Asst. Professor	Mobile robotics, Autonomous driving
Team member	Li Sun	NIO Inc., Chief Scientist	Mobile robotics, Autonomous driving
Team member	Fahad Lateef	UTBM, CIAD Lab, Ph.D. Student	Machine learning, Computer vision
Team advisor	Yassine Ruichek	UTBM, CIAD Lab, Professor	Image processing, Computer vision
Team member	Nathan Crombez	UTBM, CIAD Lab, Asst. Professor	Visual servoing, Robotics
Team member	Thomas Duvinage	UTBM, Undergraduate	Computer science
Team member	Ahmed Noubli	UTBM, Undergraduate	Computer science
Team member	Jocelyn Buisson	UTBM, CIAD Lab, Research Eng.	Software engineering, Simulation



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**HP etc.** <https://epan-utbm.github.io/epaner/>